

L Number	Hits	Search Text	DB	Time stamp
2	33922	position adj detection	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/01 13:44
4	133957	linear near2 movement or rotational near2 movement	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/01 13:44
5	951	(position adj detection) and (linear near2 movement or rotational near2 movement)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/01 13:44
6	243	((position adj detection) and (linear near2 movement or rotational near2 movement)) and (absolut\$3 adj track\$3 or detect\$4 adj (unit or device))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/01 13:44
7	91	((position adj detection) and (linear near2 movement or rotational near2 movement)) and (absolut\$3 adj track\$3 or detect\$4 adj (unit or device)) and head\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/01 13:44
10	635	((position adj detection) and (linear near2 movement or rotational near2 movement)) and (absolut\$3 adj track\$3 or detect\$4 adj (unit or device or position))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/01 13:45
11	155	((position adj detection) and (linear near2 movement or rotational near2 movement)) and (absolut\$3 adj track\$3 or detect\$4 adj (unit or device or position)) and (cod\$3)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/01 13:45
1	28	absolut\$3 adj track\$3 and detect\$4 adj (unit or device)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/01 13:45
3	5	(position adj detection) and (absolut\$3 adj track\$3 and detect\$4 adj (unit or device))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/01 13:45
8	9	((position adj detection) and (linear near2 movement or rotational near2 movement)) and (absolut\$3 adj track\$3 or detect\$4 adj (unit or device)) and head\$1 and (cod\$3 and array\$3)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/01 13:45
9	17	((position adj detection) and (linear near2 movement or rotational near2 movement)) and (absolut\$3 adj track\$3 or detect\$4 adj (unit or device)) and head\$1 and (cod\$3)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/01 13:45
12	74	((position adj detection) and (linear near2 movement or rotational near2 movement)) and (absolut\$3 adj track\$3 or detect\$4 adj (unit or device or position)) and (cod\$3) and head\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/01 13:45
13	1022	(maximum or maximal) adj1 length near1 sequence	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/01 13:46
14	209	((maximum or maximal) adj1 length near1 sequence) and polynomial	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/01 13:48

15	142	((maximum or maximal) adj1 length near1 sequence) and polynomial) and detect\$3	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/01 13:48
16	30	((((maximum or maximal) adj1 length near1 sequence) and polynomial) and detect\$3) and absolut\$3	USPÄT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/01 13:56
17	112	((((maximum or maximal) adj1 length near1 sequence) and polynomial) and detect\$3) not (((maximum or maximal) adj1 length near1 sequence) and polynomial) and detect\$3) and absolut\$3)	USPÄT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/01 13:57